



## Other classes

### glSpace

OpenGLSurface that handles drawing. While there can be more than one, data cannot be shared between them.

### glFramebuffer

Convenience class for setup and maintenance of OpenGL framebuffers.

### glPointParticles

A quick-and-dirty way of using point particles, though it does require a bit of setup inside your glSpace and your glShaders.

### glShader

Maintains and updates GLSL shaders. Currently handles vertex, fragment, geometry, and tessellation control shaders.

## Data types

### glVector2D

XY data

### glVector3D

XYZ data

### glVector4D

XYZW data

### glQuaternion

XYZW data for rotation

NOTE: glMath Module handles the math operations for all of these types.

## Modules

### glMath

A collection of math functions that work with vectors, quaternions, and matrices. Also, there are several miscellaneous math functions that I've found useful enough to include here.

### ASSIMP (Open asset importer)

Handles loading of meshes from many 3D formats. While everything is parsed, not everything is currently used by XojoGL. Uses the v4.1 library for Mac and Windows.

### IntersectTests

Various 3D intersect tests. Useful for collision detection but no broad- or narrow-phase collision detection algorithms are provided.

### SimpleShaderMaker

A basic glShader creator meant to get you up and running. Can create a single diffuse texture with separate ambient, diffuse, specular, and roughness properties as well as multiple lights.

### OpenGL Declares

Used to call OpenGL commands. Includes modules up to OpenGL 4.3. CAUTION: Not every call has been properly vetted. Also includes commands for:

GL_ARB	AGL
GL_EXT	GLExtApple
GLU	
	WGL
	WGLext

\*The OS-specific commands in the right column are not fully implemented

## TRANSFORMING ELEMENTS:

Use the `glTransform3D` property to

- Position: `Transform.Position` (`glVector3D`)  
`Transform.MoveForward` (distance amount)
- Rotate: `Transform.Rotate` (`glQuaternion`; default is 0,0,0,0)  
`Transform.Pitch` (angle in radians around local X-axis)  
`Transform.Yaw` (angle in radians around local Y-axis)  
`Transform.Roll` (angle in radians around local Z-axis)
- Scale: `Transform.Scale` (`glVector3D`; default is 1,1,1)

## glGROUP3D usage:

`glGroup.Append(glComponent)`

`glGroup.Remove(component name)`

Each `glComponent` accessible from `glGroup.Child` array.

`glComponents` within array have transforms LOCAL

to the `glGroup` they are within and will be affected by any transforms performed on the `glGroup` itself.

## gIMATH MODULE

Bezier	Calculates curve using four input points and a delta time value.
Clamp	Clamps a value from going over or under the given range.
CosignInterpolate	Simple ease-in, ease-out between 0.0 <= delta <= 1.0.
Degree	Converts a radian value into a degree.
Float16ToFloat32	Decodes 16-bit half float into 32-bit float.
Float32ToFloat16	Encodes 32-bit float to a 16-bit half float.
fMod	Implementation of <code>floatMod</code> function from C.
frameToUV	Converts a given frame number and returns UV coordinates.
GetVertexData	Builds <code>MemoryBlock</code> from array of <code>Singles</code> .
glFrustum	Returns <code>glFrustum</code> matrix.
glOrtho	Returns orthographic projection matrix.
gluPerspective	Returns perspective projection matrix.
gluUnproject	Converts object coordinates to window coordinates.
LinearInterpolate	Linear interpolation between 0.0 <= delta <= 1.0.

`Print` Returns passed data type as `String`. Works with 4x4 matrices, `glVector2D`, -3D, and -4D.

### CONSTANTS

EPSILON	0.000001
k2Pi	2 * Pi
kDegreeToRadian	Multiply degree by this to get value in radians.
kMatrix4x4Size	Size of a matrix of <code>Single</code> values.
kPi	3.14
kPiOver2	Half Pi
kPiOver360	Pi / 360
kRadianToDegree	Multiply radian by this to get value in degrees.
kVector2Dsize	Size of 2 <code>Singles</code> .
kVector3Dsize	Size of 3 <code>Singles</code> .
kVector4Dsize	Size of 4 <code>Singles</code> .

### v3\_

Add	Transforms vector by adding input vector.
AngleBetween	Angle in radians between two vectors.
CosineInterpolate	Returns vector smoothly interpolated between 2 input vectors.
Cross	Returns new vector based on cross product.
CubicInterpolate	Returns vector smoothly interpolated between 2 input vectors.
Dot	Dot product with another <code>vector3D</code> .
GetMatrix	Returns vector as a 12-byte <code>MemoryBlock</code> .
IsEqual	Check is another vector is equal to me within epsilon.
Length	Length of vector.
LenSquared	Squared length of vector.
Minus	Returns new vector from subtraction between 2 vectors.
Multiply	Returns new vector from multiplying 2 vectors.
MultiplyVec3	Transforms vector by component-wise multiplication.
Negate	Returns new vector by negating all values.
Normalize	Transforms vector to unit vector via normalization.
NormalizeNew	Returns new normalized vector from input vector.
ObjectToWorldTransform	Returns world position given local position & matrix.
Plus	Returns new vector by adding input vector.
Subtract	Transforms vector by subtracting input vector.
Times	Transforms vector by multiplying input vector.
TimesVec3	Transforms vector by component-wise multiplication.
WorldToObjectTransform	Returns local position given world position & matrix.

### m44\_

Copy	Copies a 4x4 as a <code>MemoryBlock</code> .
Create4x4	Creates matrix given 16 <code>Singles</code> in row-major order.
CreateIdentity	Returns an identity matrix.
CreateModelview	Create matrix given position, Euler angles, and scale.
CreateRotate	Creates matrix for rotation.
CreateRotateX	Creates matrix for rotation around the X axis.
CreateRotateY	Creates matrix for rotation around the Y axis.
CreateRotateZ	Creates matrix for rotation around the Z axis.
CreateScale	Create a XYZ scale-only matrix.
CreateTranslate	Create a translate-only matrix.
CreateTranslateScale	Create a combined translate & scale matrix.
Decompose	Retrieve position, Euler angles, and scale from matrix.
DecomposePosition	Retrieve only XYZ position from matrix.
DecomposeRotationEuler	Retrieve only Euler angles from matrix.
DecomposeScale	Retrieve only XYZ scale from matrix.
Determinant	Returns the determinant of a matrix.
GetMultVec3	Multiply a <code>vector3D</code> and a matrix.
GetMultVec4	Multiply a <code>vector4D</code> and a matrix.
GetRotate	Multiply matrix with a 3x3 matrix.
GetRotateQuat	Multiply matrix with a quaternion.
GetScale	Multiply matrix with XYZ scale.
GetTranslate	Multiply matrix with XYZ position coordinates.
Identity	Reset passed-in matrix back to Identity matrix.
Inverse	Invert a 4x4 matrix.
IsIdentity	Determines if matrix is an Identity matrix.
LookAt	Returns matrix aiming towards desired target.
LookAtSpirt	Same as <code>LookAt()</code> , but makes matrix point towards camera.
Mult4x3	Multiplies 2 matrices, assuming last row is homogeneous.
Mult4x4	Full multiply of two matrices.
Rotate	Multiplies a transform and rotation matrix.
RotationAlign	Returns rotation matrix based on given direction.
Scale	Scales a matrix by XYZ scale.
SetRotate	Set rotation part of matrix by input quaternion.
SetTranslate	Set position part of matrix by input <code>vector3D</code> .
Translate	Multiply matrix by input position vector.
TranslateScale	Multiply matrix by input position & scale vectors.
Transpose	Transpose given matrix.

`glVector2D` and `glVector4D` functions work similarly to their `glVector3D` counterpart.

### v2\_

Add
CosineInterpolate
IsEqual
Length
LenSquared
Minus
Multiply
Normalize
Plus
Subtract
Times

### v4\_

Add
DotPlane
GetMtarix
IsEqual
Length
LenSquared
Minus
Multiply
Normalize
NormalizePlane
Plus
Subtract
Times